

**NASA Contractor Report 4117**

**High-Speed Assembly Language  
(80386/80387) Programming  
for Laser Spectra Scan  
Control and Data Acquisition  
Providing Improved Resolution  
Water Vapor Spectroscopy**

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## ABSTRACT

An assembly language program using the Intel 80386 CPU and 80387 math co-processor chips was written to increase the speed of data gathering and processing, and provide control of a scanning CW ring dye laser system. This laser system is used in high resolution (better than  $0.001\text{ cm}^{-1}$ ) water vapor spectroscopy experiments. Laser beam power is sensed at the input and output of white cells and the output of a Fabry-Perot. The assembly language subroutine is called from Basic, acquires the data and performs various calculations at rates greater than 150 times faster than could be performed by the higher level language. The width of output control pulses generated in assembly language are 3 to 4 microseconds as compared to 2 to 3.7 milliseconds for those generated in Basic (about 500 to 1000 times faster).

Included are a block diagram and brief description of the spectroscopy experiment, a flow diagram of the basic and assembly language programs, listing of the programs, scope photographs of the computer generated 5-volt pulses used for control and timing analysis, and representative water spectrum curves obtained using these programs.

HIGH-SPEED ASSEMBLY LANGUAGE (80386/80387) PROGRAMMING  
FOR LASER SPECTRA SCAN CONTROL AND DATA ACQUISITION  
PROVIDING IMPROVED RESOLUTION WATER VAPOR SPECTROSCOPY

By

Robert J. Allen

INTRODUCTION

This report describes an Intel 80386 and 80387 assembly language program written to increase the speed of data gathering and processing, and provide control of a scanning CW ring dye laser system. This laser system is used in high resolution Water Vapor Spectroscopy Experiments. The 80386 is a 32-bit CPU chip operating at 16 MHz in a Compaq 386 computer, and the 80387 is a high speed math coprocessor. The assembly language subroutine is called from BASICA.

The program was originally written for the Compaq Portable 286 computer using the 80286 and 80287 chips. It was later updated for use with the faster Compaq 386.

WATER VAPOR SPECTROSCOPY EXPERIMENTS

A block diagram of the spectroscopy experiment is shown in Fig. 1. # An argon laser pumps a tunable CW ring dye laser. After receiving a Laser Scan Trigger, the Scanning Electronics will cause a very narrow line-width (0.0001 pm) laser beam to be outputted at wavelengths within pre-selected limits, for

-----  
# Figures 1 and 3 were provided by Dr. Benoist Grossmann, project scientists conducting the water vapor spectroscopy experiments.

example, 726.000 to 726.050 nm. This 50 pm scanning range can be selected anywhere between 725 nm (13,793.1 cm<sup>-1</sup>) to 730 nm (13,698 cm<sup>-1</sup>). A portion of the output beam is directed by beamsplitters to a Monochrometer for absolute wavelength calibration, a Fabry-Perot and photodiode P4 to provide the wavelength markers, and P3 as the Power Reference. The remaining beam is routed through White Cells #1 and #2 and sensed by photodiodes P1 and P2.

The outputs from the four photodiodes, P1-P4, are amplified and routed to four analog input channels multiplexed into a 10 KHz analog-to-digital converter with 12-bit resolution (A/D Board). The four multiplexed digital outputs are then processed as described later in this report. The A/D Board is part of an IBM Data Acquisition and Control Adapter card that fits inside the Compaq. This Adapter also contains two analog output channels; a 16-bit digital input port; a 16-bit digital output port; a 32-bit timer; and a 16-bit, externally-clocked, timer/counter. One bit of the digital output port is available for use as the Laser Scan Trigger.

#### CHOICE OF ASSEMBLY LANGUAGE PROGRAMMING

Since the four readings from photodiodes P1-P4 averaged N times are a single point on a rapidly changing plot of a single water vapor line, this data set should be obtained as rapidly as the hardware allows. More time, if needed, can be used to start the repeat (R) of subsequent data sets since this time is the separation between data points. Separation time, however,

should also be kept to a minimum since it is associated with the resolution of the curve.

As indicated in the general literature and by Rollins (1985), "assembly language is by far the fastest, most flexible, and most compact of all programming languages. It shows how and why higher-level languages operate. It gives access to features of a machine that are inaccessible with other languages." An assembly language matrix multiplication routine published by Startz (1985) is about 150 times faster than pre-8087 Basic.

Fortunately, assembly language routines are easily combined with either interpreted or compiled Basic, as well as with programs written in other high-level languages. The main program illustrated in this report was written in Basic (BASICA.COM) calling the assembly language routine for acquiring N sets of the four photodiode (P1-P4) readings and performing required calculations.

#### DESCRIPTION OF PROGRAMS

The basic program (Table II) and assembly language program (Table III) were prepared as part of this task and provided to the Project Scientists. He incorporated them into his Basic program which included plotting features for use in the high resolution spectroscopy experiments.

Figure 2 contains a flow diagram of both programs. Basic is used first (prior to scanning) to calculate and display the 'mean' value of the background noise (W, X, Y & Z) from each of the four photodiodes (P1-P4). Scanning is initiated and the assembly language program called. The output from each of the

photodiodes are read and the corresponding background noise subtracted. The differences from P1, P2 and P4 are then normalized to the power reference difference P3. This process is repeated N times and the 'mean' of each of the three ratios  $((P1-X)/(P3-W))$ ,  $((P2-Y)/(P3-W))$ , and  $((P4-Z)/(P3-W))$  calculated. The process then returns to Basic where the 'mean' of these three ratios are displayed. Each of the ratios constitute a single data point on each of three curves. The above process is then repeated R times obtaining new data points while the laser continues to scan. BASICA line numbers are then displayed for the background sample size (M), data sample size (N) and number of repeats during laser scanning (R). The results, when coupled with the plotting program, are the curves shown in Figures 3A and B.

Five-volt pulses, BO-0 and BO-1, are generated in Basic prior to scanning and can be used to trigger a scope and to initiate scanning. Binary output pulses, BO-2 and BO-3, are generated in Assembly Language and were used to measure the time for different processes during program development such as the:

- (1) greater-than 20 microsecond delay time required to allow transients to settle following each multiplexed operation,
- (2) total time used to read the four analog input from the photodiodes and subtract the backgrounds from each, and
- (3) time to calculate the mean of the ratios.

Scope photographs of pulses BO-0 to BO-3, their pulse widths, and various times are shown in Figure 4 and Table I.



## FORMULATING THE PROGRAMS

The assembly language program was written using WordStar, assembled using Microsoft Macro-Assembler version 4.00 (MASM ALLEN7R) and linked for high memory residence (LINK/H ALLEN7R). Debug was called (SYMDEB ALLEN7R.EXE) and Basic entered using N BASICA.COM. L and G. ALLENB7R.BAS was then loaded and a binary file created using DEF SEG = &H9FCA followed by BSAVE "ALLEN7R.BIN",0,&h178. Running ALLENB7.BAS produced the display shown in Table IIB.

## ACKNOWLEDGMENT

Publications by Lafore (1984) and Startz (1985) provided excellent references supporting the assembly language portions of this task. The author wishes to thank Dr. Jerry Tucker of NASA Langley Research Center for his helpful suggestion in connection with the assembly language programming, Dr. Benoist Grossmann for providing the information concerning the experiments and review of this report, and Patrick Ponsardin for his review and comments concerning this report. Both Benoist and Patrick are affiliated with Old Dominion University Research Foundation (on leave from Electricite de France).

## REFERENCES

Rollins, Dan (1985), "IBM-PC 8088 MACRO Assembler Programming", Macmillan Publishing Co.

Startz, Richard (1985), "8087 Applications and Programming for the IBM PC, XT, and AT", Brady Communications Co., Inc. NY, NY 10020.

Lafore, Robert (1984), "Assembly Language Primer for the IBM PC & XT", A Plume/Waite Book.

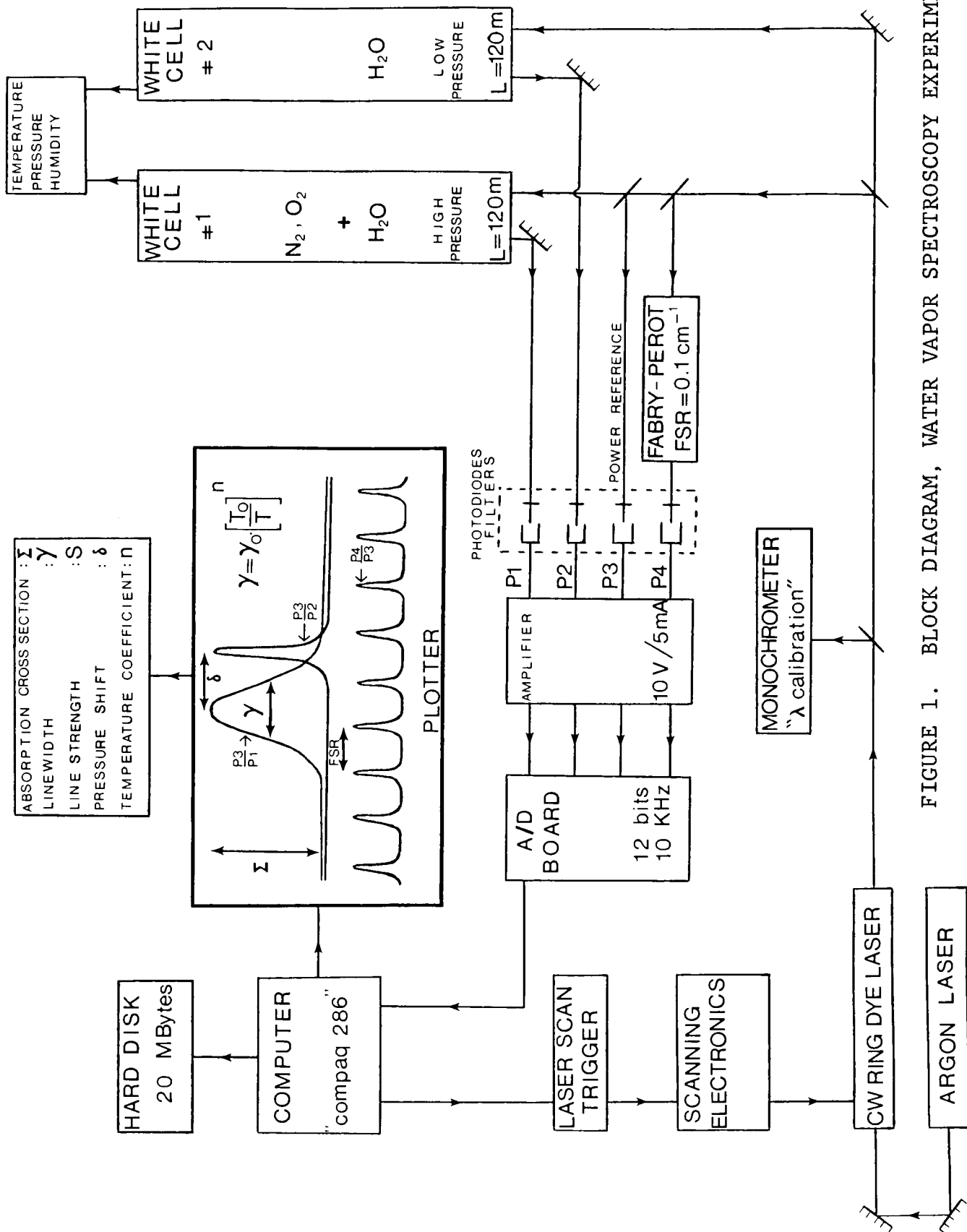


FIGURE 1. BLOCK DIAGRAM, WATER VAPOR SPECTROSCOPY EXPERIMENT.

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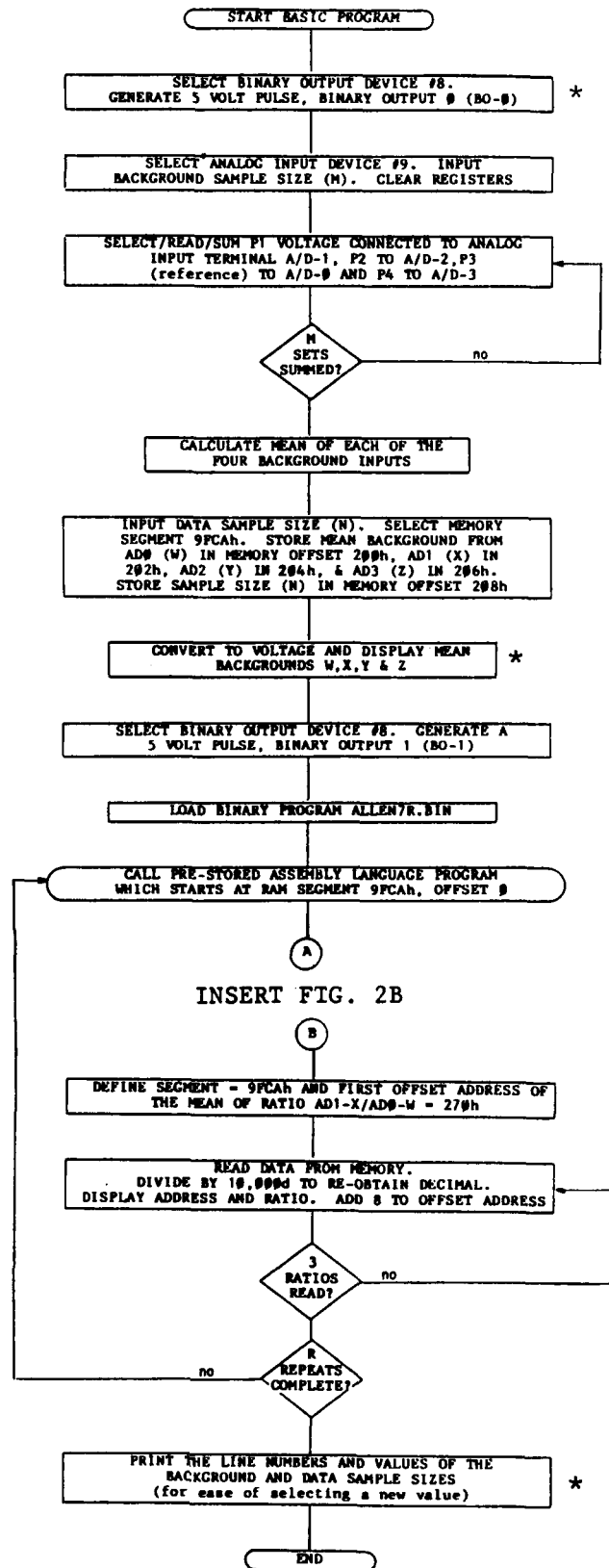
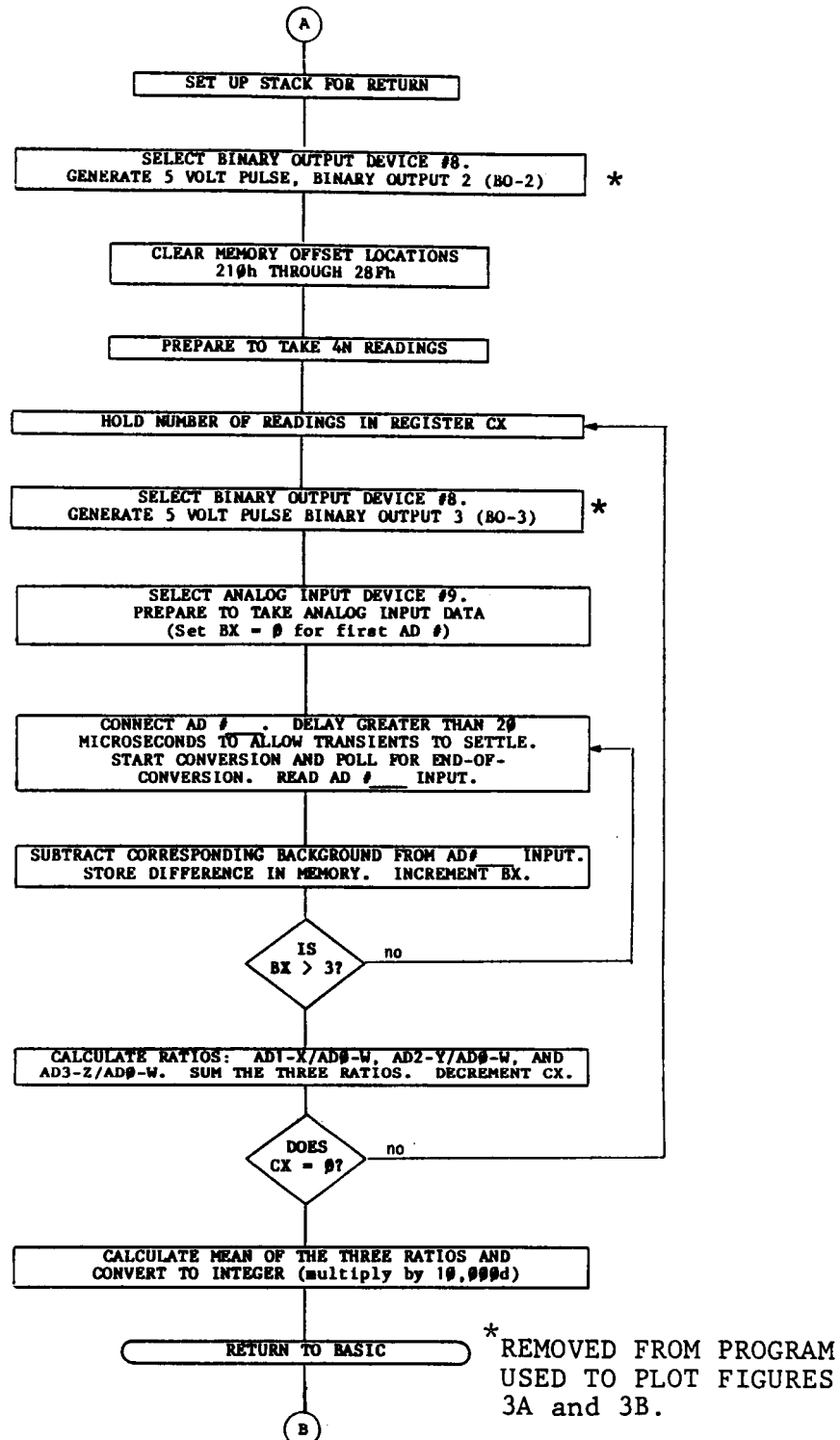


FIGURE 2A. FLOW DIAGRAM OF THE BASIC PROGRAM.

FROM FIG. 2A



TO FIG. 2A

FIGURE 2B. FLOW DIAGRAM OF THE 80386/80387 ASSEMBLY  
LANGUAGE PROGRAM.

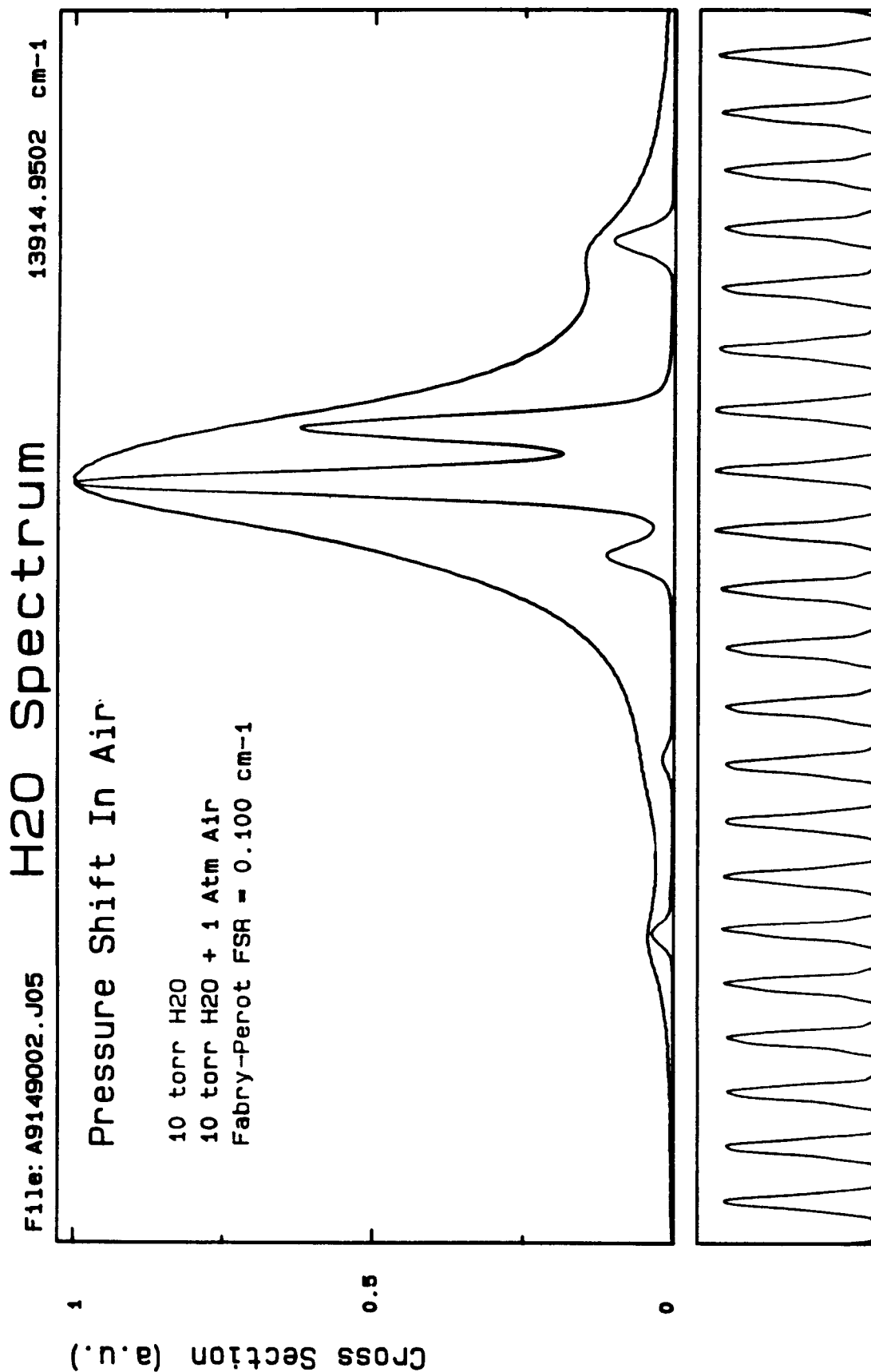


FIGURE 3A. CROSS SECTION VS. WAVENUMBER SHOWING PRESSURE SHIFT  
IN AIR FOR THE LINE CENTERED AT 13914.9502 cm<sup>-1</sup>.

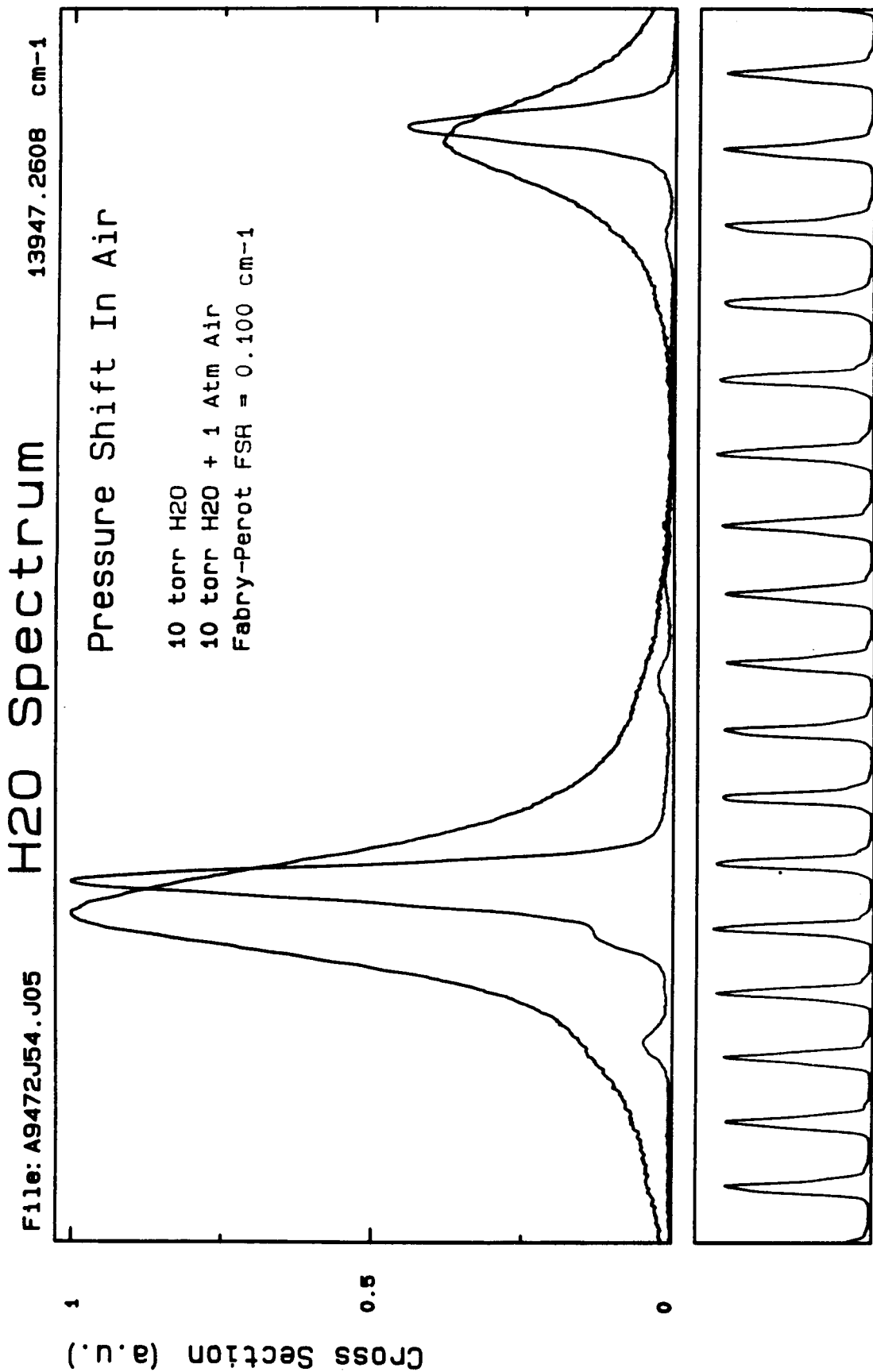
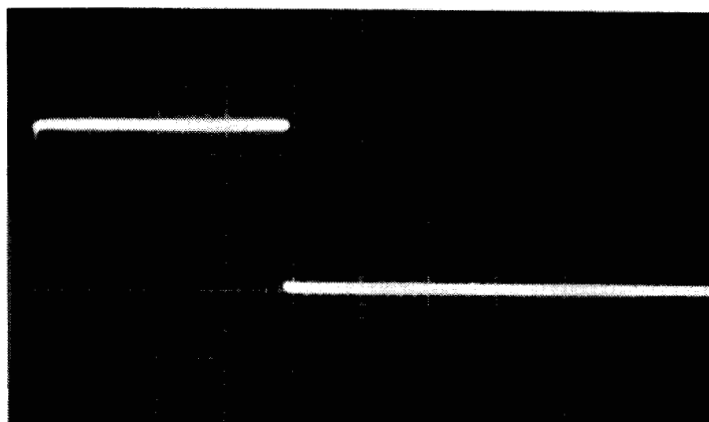


FIGURE 3B. CROSS SECTION VS. WAVENUMBER SHOWING PRESSURE SHIFT  
 IN AIR FOR THE LINE CENTERED AT 13947.2608 cm<sup>-1</sup>.

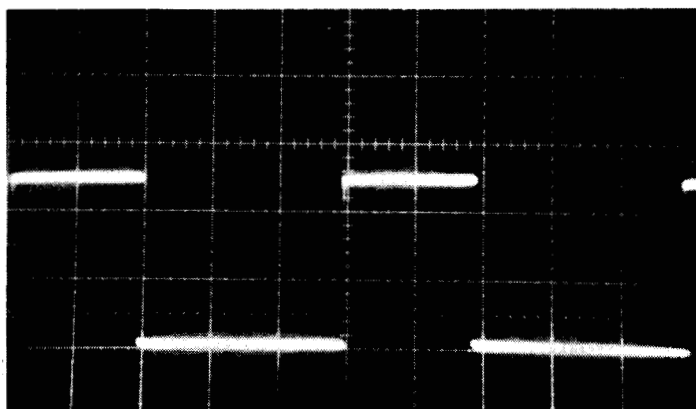


(A) 5V 3.7 ms wide  
Binary Output  
pulse BO-0

2V/div 0.5 ms/div

(added program:  
1035 GOTO 80)

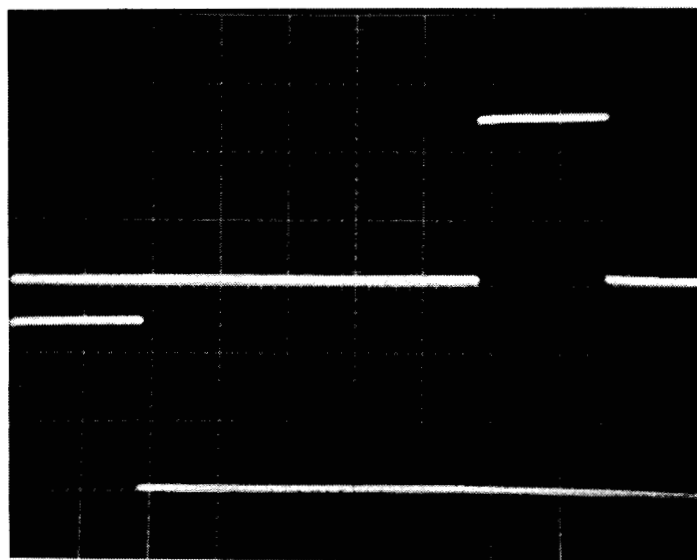
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(B) 5V 2 ms wide  
Binary Output  
pulse BO-1

2V/div 1 ms/div

(added program:  
1105 GOTO 1060)



(C) BO-0

2V/div 1 ms/div

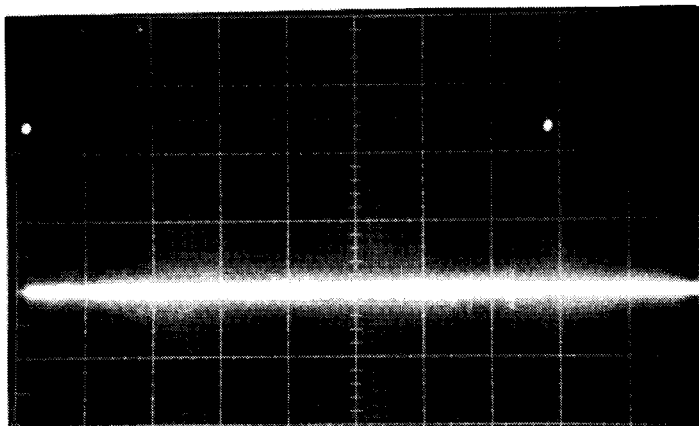
(D) BO-1 (scope trig)

2V/div 1 ms/div

(added program:  
1105 GOTO 80)

FIGURE 4. SCOPE PHOTOGRAPHS OF 5-VOLT PULSES GENERATED FROM BINARY OUTPUTS BO-0 TO BO-3. PULSE WIDTHS AND VARIOUS PROGRAM TIMES ARE LISTED IN TABLE I.

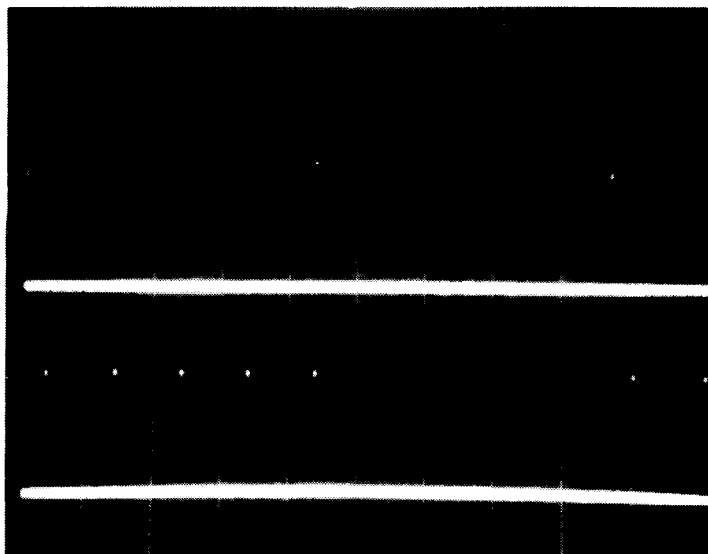




(E) BO-1

2V/div 100 ms/div

(added program:  
1395 GOTO 1060)



(F) BO-2

2V/div 1 ms/div

(G) BO-3

2V/div 1 ms/div

(added program:  
1185 GOTO 1160)

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(H) BO-1 ADDED TO  
INTENSIFIED BO-2

(added program:  
1185 GOTO 1060)

TABLE I. PROGRAM TIMES DETERMINED USING BINARY OUTPUT PULSES  
SHOWN IN FIGURE 4

BASICA LINE NUMBERS	ADDED PROGRAM STEP *	GENERATED BINARY OUTPUT PULSE	TIME FROM START OF BO-i TO START OF BO-j
80-140	1035 GOTO 80	BO-0, 5V 3.7 ms wide (FIG. 4A)	BO-0 to BO-0: 200 ms (M=1) 412 ms (M=10) 875 ms (M=30) 2500 ms (M=100)
1060-1100	1105 GOTO 1060	BO-1, 5V 2 ms wide (FIG. 4B)	BO-1 to BO-1: 3 ms
80-1100	DELETE 1040 1105 GOTO 80	BO-0 and BO-1 (FIG. 4C&D)	BO-0 to BO-1: 200 ms (M=1) BO-1 to BO-0: 6.8 ms
1060-1390	1395 GOTO 1060	BO-1 (FIG. 4E)	BO-1 to BO-1: 770 ms
1160-1185 includes total assembly language subroutine	1185 GOTO 1160	BO-2 & BO-3 3.5V into 10K WIDTHS: 3 us (BO-2) 4 us (BO-3) (FIG. 4F&G)	BO-2 to BO-2: 4.5 ms (N=1) 6.5 ms (N=3) 8.5 ms (N=5) 43.2 ms (N=40)  FOR N=5: BO-2 to BO-3 -- 0.31 ms BO-31 to BO-32 -- 1.0 ms BO-35 to BO-2 -- 4.2 ms
1060-1185 includes total assembly language subroutine	1185 GOTO 1060	BO-1 ADDED TO INTENSIFIED BO-2. (BO-2 into 10K) (FIG. H)	BO-1 to BO-2: -- 29.6 ms BO-2 to BO-1: -- 10.4 ms BO-1 to BO-1: -- 40 ms

\*Added program to produce a repetitive pulse for timing analyses  
and scope photographic purposes.

# TABLE IIA BASIC PROGRAM ALLENB7R.BAS

```

10 CLS '--- WATER VAPOR SPECTROSCOPY EXPERIMENT, CONTROL & DATA PROCESSING ---
20 '
30 'GENERATES BINARY OUTPUT PULSE BO 0, CALCULATES THE MEAN OF M SETS OF THE
BACKGROUND DATA FROM AD0-AD3, POKES THE FOUR BACKGROUND VALUES & THE DATA
SAMPLE SIZE N INTO MEMORY, CONVERTS THE FOUR INTO A VOLTAGE, AND DISPLAYS THEIR
VALUES.
40 ' CALLS THE ASSEMBLY LANGUAGE PROGRAM. AFTER RETURNING TO BASIC, DIVIDES
THE THREE CALCULATED DATA RATIOS (corrected for background noise) BY 10,000,
AND DISPLAYS THESE RATIOS.
50 ' THE ASSEMBLY LANGUAGE PROGRAM IS AGAIN CALLED AND THE PROCESS REPEATED
R TIMES. THE PROGRAM LISTING FOR THE BACKGROUND SAMPLE SIZE (M), DATA SAMPLE
SIZE (N) AND THE NUMBER OF REPEATS DURING LASER SCANNING (R) ARE DISPLAYED FOR
EASE OF CHANGE.
60 '
70 ' ***** GENERATE BINARY OUTPUT PULSE BO 0 *****
80 OUT 49890!,8 'Selects Reg. 12, Device 8
90 OUT 8930,0 'Zero volts from BO 0 (low byte)
100 OUT 8931,0 'Zero volts from BO 0 (high byte)
110 OUT 8930,1 '5 volts from BO 0 (low byte)
120 OUT 8931,0 ' (high byte) SCOPE TRIG +
130 OUT 8930,0 'Zero volts from BO 0 (low byte)
140 OUT 8931,0 ' (high byte) START MEASURING BACKGROUND
150 ' ***** TAKE THE MEAN OF BACKGROUND READINGS FROM AD0-AD3 *****
160 OUT 49890!,9 'BASIC ADDRESS OF DATA ACQ ADAPTER 0 = 2E2H (AD# INPUTS)
170 M = 30 'BACKGROUND SAMPLE SIZE, M
180 AL=0:AH=0:BL=0:BH=0:CL=0:CH=0:DL=0:DH=0
190 WL=0:WH=0:XL=0:XH=0:YL=0:YH=0:ZL=0:ZH=0
200 FOR J=1 TO M
210 OUT 738,0
220 OUT 738,0 'SELECT AD 0 (P1)
230 OUT 739,0
240 OUT 738,1
250 OUT 739,0
260 OUT 738,0
270 OUT 739,0
280 AL=INP (8930) 'READ AD 0
290 WL=WL+AL
300 AH=INP (8931)
310 WH=WH+AH 'SUM AD 0
320 OUT 738,0 'SELECT/READ/SUM AD 1 (P2)
330 OUT 739,1
340 OUT 738,1
350 OUT 739,1
360 OUT 738,0
370 OUT 739,1
380 BL=INP (8930)
390 XL=XL+BL
400 BH=INP (8931)
410 XH=XH+BH
420 OUT 738,0 'SELECT/READ/SUM AD 2 (P3)
430 OUT 739,2
440 OUT 738,1
450 OUT 739,2
460 OUT 738,0
470 OUT 739,2
480 CL=INP (8930)
490 YL=YL+CL
500 CH=INP (8931)
510 YH=YH+CH

```

```

520 OUT 738,0      'SELECT/READ/SUM AD 3 (P4)
530 OUT 739,3
540 OUT 738,1
550 OUT 739,3
560 OUT 738,0
570 OUT 739,3
580 DL=INP (8930)
590 ZL=ZL+DL
600 DH=INP (8931)
610 ZH=ZH+DH
620 NEXT J          'REPEAT SELECT/READ/SUM DATA SET AD 0 - AD 3
630 '
640 WL=WL/M          'MEAN OF BACKGROUND READINGS FROM AD 0
650 WH=WH/M
660 XL=XL/M          'MEAN OF BACKGROUND READINGS FROM AD 1
670 XH=XH/M
680 YL=YL/M          'MEAN OF BACKGROUND READINGS FROM AD 2
690 YH=YH/M
700 ZL=ZL/M          'MEAN OF BACKGROUND READINGS FROM AD 3
710 ZH=ZH/M
720 '
730 N = 5            'DATA SAMPLE SIZE, N
740 '
750 ' ***** STORE MEAN BACKGROUND READINGS AND N IN MEMORY *****
760 DEF SEG = &H9FCA 'SEGMENT ADDRESS (page 426)
770 ADDR = &H200
780 POKE ADDR,WL      'SAVE AD 0 BACKGROUND IN MEMORY 200H
790 ADDR=ADDR+1
800 POKE ADDR,WH
810 ADDR=ADDR+1
820 POKE ADDR,XL      'SAVE AD 1 BACKGROUND IN MEMORY 202H
830 ADDR=ADDR+1
840 POKE ADDR,XH
850 ADDR=ADDR+1
860 POKE ADDR,YL      'SAVE AD 2 BACKGROUND IN MEMORY 204H
870 ADDR=ADDR+1
880 POKE ADDR,YH
890 ADDR=ADDR+1
900 POKE ADDR,ZL      'SAVE AD 3 BACKGROUND IN MEMORY 206H
910 ADDR=ADDR+1
920 POKE ADDR,ZH
930 ADDR = &H208
940 POKE ADDR,N        'SAVE DATA SAMPLE SIZE, N, IN MEMORY 208H
950 '
960 ' ***** CONVERT TO VOLTAGE AND DISPLAY *****
970 W=.00244*(256*WH+WL)
980 X=.00244*(256*XH+XL)
990 Y=.00244*(256*YH+YL)
1000 Z=.00244*(256*ZH+ZL)
1010 PRINT "BACKGROUND","W","X","Y","Z"
1020 PRINT ,W,X,Y,Z
1030 PRINT
1040 STOP
1050 '***** GENERATE BINARY OUTPUT PULSE BO1 *****
1060 OUT 49890!,8      'Selects Reg. 12, Device 8
1070 OUT 8930,2        '5 volts from BO 1 (low byte)
1080 OUT 8931,0        ' (high byte) 4-CHANNEL MARKER
1090 OUT 8930,0        'Zero volts from BO 1 (LOW BYTE)
1100 OUT 8931,0        'Zero volts from BO 1 (high byte)

```

```

1110 '##### PREPARE FOR ASSEMBLY LANGUAGE PROGRAM #####
1120 BLOAD "ALLEN7R.BIN",0      '(R. L. Lafore, page 428)
1130 R = 300      'NUMBER OF REPEATS DURING LASER SCANNING, R
1140 R = 3      'NUMBER OF REPEATS DURING LASER SCANNING, R
1150 FOR S=1 TO R
1160 CALL ALLEN7R
1170 ' ##### GO TO ASSEMBLY LANGUAGE PROGRAM #####
1180 '----- RETURN FROM ASSEMBLY LANGUAGE PROGRAM -----
1190 '***** DISPLAY DATA CALCULATED IN ASSEMBLY LANGUAGE *****
1200 DEF SEG = &H9FCA
1210 ADDR = &H270
1220 PRINT "DATA OFFSET ADDRESS",,"RATIO"
1230 FOR K=1 TO 3
1240 EL = PEEK(ADDR)
1250 EH = PEEK(ADDR+1)
1260 E=(256*EH+EL)
1270 PRINT " " " HEX$(ADDR),
1280 PRINT USING " ##.## ";E
1290 F=E/10000
1300 PRINT ",,F
1310 ADDR = ADDR+8
1320 NEXT K
1330 NEXT S
1340 PRINT
1350 ' ***** DISPLAY SAMPLE SIZE OF CALCULATED DATA *****
1360 PRINT "170 M ="M " 'BACKGROUND SAMPLE SIZE, M
1370 N = PEEK(&H208)
1380 PRINT "730' N ="N " 'DATA SAMPLE SIZE, N
1390 PRINT "1140 R ="R" 'NUMBER OF REPEATS DURING LASER SCANNING, R
1400 END
1410 'SAVE"ALLENB7R 11/3/87
Ok

```

TABLE IIB      DISPLAY PRODUCED BY RUNNING ALLENB7R.BAS

Break in 1040

Ok

CONT

DATA OFFSET	ADDRESS		RATIO
	270	%21154.0	
			2.1154
	278	%31532.0	
			3.1532
	280	%42287.0	
			4.2287

DATA OFFSET	ADDRESS		RATIO
	270	%21053.0	
			2.1053
	278	%31361.0	
			3.1361
	280	%42071.0	
			4.2071

DATA OFFSET	ADDRESS		RATIO
	270	%21055.0	
			2.1055
	278	%31418.0	
			3.1418
	280	%42143.0	
			4.2143

170 M = 30

730' N = 5

1140 R = 3

Ok

'BACKGROUND SAMPLE SIZE, M

'DATA SAMPLE SIZE, N

'NUMBER OF REPEATS DURING LASER SCANNING, R

# TABLE IIIA ASSEMBLY LANGUAGE PROGRAM ALLEN7R.LST

Microsoft (R) Macro Assembler Version 4.00

10/29/87 14:49:17  
Page 1-1

```

;ALLEN7R --.EXE file to be controlled by BASIC
;
; Generates a BINARY OUTPUT PULSE (BO2) to
; indicate the START of taking data, follow-
; ed by a BO3 pulse to be used as a marker
; at the start of each set of ADC INPUTS.
; Reads data from AD0 and subtracts W (poked
; into RAM previously from BASICA) and holds
; the DIFFERENCE, then reads data from AD1
; and subtracts X and holds this DIFFERENCE,
; etc. for AD2-Y and AD3-Z. This is repeat N
; time where 2>N>100 which was previously
; poked from BASICA. A maximum of four
; memory locations (200H, 202H, 204H, & 206H)
; are required for the BACKGROUND data pre-
; viously averaged in BASIC; and four memory
; locations (210H, 218H, 220H, & 228H) for
; subtracted data, three memory locations
; (230H, 238H, & 240H) for the RATIO data,
; one (248H) for the value of N, three
; (250H, 258h, & 260H) for the summation of
; RATIOS, and the same three (250H, 258H,
; & 260H) for the MEAN of the RATIOS all
; obtained in this ASSMEBLY LANGUAGE program.
; The values are then multiplied by 10,000d
; to eliminate the decimal point. The prog-
; ram then returns to basic.
;          BASICA PROGRAM -- ALLENB7R.BAS
;-----
.287

;*****

0000          ST_SEG  SEGMENT STACK  ;DEFINE STACK SEGMENT
0000 0014{    DB      20 DUP  ('STACK  ')
              53 54 41 43 4B
              20 20 20
              ]

00A0          ST_SEG  ENDS

;*****

0000          PROGNAM SEGMENT          ;DEFINE CODE SEGMENT

;-----
0000          MAIN    PROC    FAR      ;MAIN PART OF PROGRAM

              ASSUME  CS:PROGNAM,DS:NOTHING

0000          START:          ;START EXECUTION ADDR

```

```

                                ;SET UP STACK FOR RETURN (p 439)
0000 55                        PUSH BP          ;SAVE BP
0001 1E                        PUSH DS          ;SAVE OLD DATA SEGMENT
0002 56                        PUSH SI          ;SAVE OLD SI
0003 8C C8                     MOV AX,CS        ;DATA SEGMENT SAME AS
0005 8E D8                     MOV DS,AX        ; CODE SEGMENT
0007 2B C0                     SUB AX,AX        ;ZERO AX
0009 50                        PUSH AX          ;SAVE IT ON STACK

                                ;SELECT/HOLD DATA ACQ/CTRL ADAPT--BINARY
000A BA C2E2                   MOV DX,0C2E2H    ;REG 12,ADPTR 0,LO B
000D B8 0008                   MOV AX,8        ;BINARY DEVICE 8
0010 EE                        OUT DX,AL        ; LOW BYTE OUTPUT
0011 BA C3E3                   MOV DX,0C3E3H    ;REG 12,ADPTR 0,HI B
0014 B8 0000                   MOV AX,0        ;BINARY DEVICE 8
0017 EE                        OUT DX,AL        ; HIGH BYTE OUTPUT

                                ;Select Binary Output (Write), register 2
                                ; Set BO 2 TTL output low
0018 BA 22E2                   MOV DX,22E2H    ;REG 2,BIN OUT,LO B
001B B8 0000                   MOV AX,0        ;BO 2 = 0 (LO & HI)
001E EE                        OUT DX,AL        ;OUTPUT LOW BYTE
001F BA 22E3                   MOV DX,22E3H    ;REG 2,BIN OUT,HI B
0022 EE                        OUT DX,AL        ;OUTPUT HIGH BYTE

                                ; Set BO 2 TTL output high
0023 BA 22E2                   MOV DX,22E2H    ;REG 2,BIN OUT,LO B
0026 B0 04                     MOV AL,4        ;BO 2 = 1, LO B
0028 EE                        OUT DX,AL        ;OUTPUT LOW BYTE
0029 BA 22E3                   MOV DX,22E3H    ;REG 2,BIN OUT,HI B
002C B0 00                     MOV AL,0        ;HIGH BYTE OF BO 2=0
002E EE                        OUT DX,AL        ;OUTPUT HIGH BYTE

                                ; Set BO 2 TTL output low
002F BA 22E2                   MOV DX,22E2H    ;REG 2,BIN OUT,LO B
0032 B0 00                     MOV AL,0        ;BO 2 = 0 (LO & HI)
0034 EE                        OUT DX,AL        ;OUTPUT LOW BYTE
0035 BA 22E3                   MOV DX,22E3H    ;REG 2,BIN OUT,HI B
0038 EE                        OUT DX,AL        ;OUTPUT HIGH BYTE

                                ;Fill memory offset locations
0039 BB 0210                   MOV BX,0210H    ;OFFSET FILL ADDR.
003C 8B FB                     MOV DI,BX        ; INTO REG. DI
003E B9 0080                   MOV CX,80H     ;# LOCATIONS TO FILL
0041 B8 0000                   MOV AX,0000H    ;PUT # INTO AX
0044 89 05                     MOV [DI],AX    ;FILL MEMORY WITH #s
0046 47                       INC DI          ;INCREASE ADDR. BY 1
0047 E2 FB                     LOOP FILL        ;REPEAT FILLING

                                ;Prepare to Take 4N readings
0049 BB 0208                   MOV BX,0208H    ;N POKED FROM BASIC is
004C 8B 0F                     MOV CX,[BX]    ;# OF READ. TO AVERAGE
004E BB 0210                   MOV BX,0210H    ;OFFSET DATA ADDR.
0051 8B FB                     MOV DI,BX        ; INTO REG. DI

```



```

0053 B0 04          MOV AL,4          ;# OF ADC CHANNELS
0055 51             NEWSET: PUSH CX    ;HOLD # OF READING 4*N

;SELECT/HOLD DATA ACQ/CTRL ADAPT--BINARY
0056 BA C2E2        MOV DX,0C2E2H    ;REG 12,ADPTR 0,LO B
0059 B8 0008        MOV AX,8         ;BINARY DEVICE 8
005C EE            OUT DX,AL         ; LOW BYTE OUTPUT
005D BA C3E3        MOV DX,0C3E3H    ;REG 12,ADPTR 0,HI B
0060 B8 0000        MOV AX,0         ;BINARY DEVICE 8
0063 EE            OUT DX,AL         ; HIGH BYTE OUTPUT

;Select Binary Output (Write), register 2
; Set BO 3 TTL output high (WAS LOW)
0064 BA 22E2        MOV DX,22E2H    ;REG 2,BIN OUT,LO B
0067 B0 08          MOV AL,8         ;BO 3 = 1, LO B
0069 EE            OUT DX,AL         ;OUTPUT LOW BYTE
006A BA 22E3        MOV DX,22E3H    ;REG 2,BIN OUT,HI B
006D B0 00          MOV AL,0         ;HIGH BYTE OF BO 3=0
006F EE            OUT DX,AL         ;OUTPUT HIGH BYTE

; Set BO 3 TTL output low
0070 BA 22E2        MOV DX,22E2H    ;REG 2,BIN OUT,LO B
0073 B0 00          MOV AL,0         ;BO 3 = 0 (LO & HI)
0075 EE            OUT DX,AL         ;OUTPUT LOW BYTE
0076 BA 22E3        MOV DX,22E3H    ;REG 2,BIN OUT,HI B
0079 EE            OUT DX,AL         ;OUTPUT HIGH BYTE

;SELECT/HOLD DATA ACQ/CTRL ADAPT--ANALOG INPUT
007A BA C2E2        MOV DX,0C2E2H    ;REG 12,ADPTR 0,LO B
007D B0 09          MOV AL,9         ;DEVICE 9 LOW BYTE
007F EE            OUT DX,AL         ;OUTPUT LOW BYTE
0080 BA C2E3        MOV DX,0C2E3H    ;REG 12,ADPTR 0,HI B
0083 B0 00          MOV AL,0         ;DEVICE 9 HIGH BYTE
0085 EE            OUT DX,AL         ;OUTPUT HIGH BYTE

;PREPARE TO TAKE ANALOG INPUT DATA
0086 2B DB          SUB BX,BX        ;ZERO BL (AD# = AD0)

;Select Analog Input Control Reg 0 (AD#)
; Connect AD#. Hold conv (reset bit #0 to 0)
0088 BA 02E2        MOV DX,02E2H    ;REG 0,AD# INPUT,LO
NEXTAD: MOV AL,0     ;HOLD CONVERT
008B B0 00          OUT DX,AL        ;OUTPUT LOW BYTE
008D EE            MOV DX,02E3H    ;REG 0, AD# INPUT, HI
008E BA 02E3        MOV AL,BL        ;CODE FOR AD# 0 thru 3
0091 8A C3          MOV AL,BL        ;CODE FOR AD# 0 thru 3
0093 EE            OUT DX,AL        ;OUTPUT HIGH BYTE

; Delay >20 us (allow transients to settle)
0094 B9 0022        MOV CX,0022H    ;MEASURED DELAY: 26us

0097 E2 FE          TRANS: LOOP TRANS ;EXECUTE DELAY #1

; Start Conversion (set bit #0 to 1)
0099 BA 02E2        MOV DX,02E2H    ;REG 0, AD# INPUT, LO

```

```

009C B0 01          MOV AL,1          ;START CONVERT,LOW B
009E EE            OUT DX,AL          ;OUTPUT LOW BYTE
009F BA 02E3        MOV DX,02E3H      ;REG 0, AD# INPUT, HI
00A2 8A C3          MOV AL,BL         ;CODE FOR AD# 0 thru 3
00A4 EE            OUT DX,AL          ;OUTPUT HIGH BYTE

; Wait for BUSY STATE bit 0 = 0 (Polling)
00A5 BA 02E2        MOV DX,02E2H      ;REG 0, LOW BYTE
00A8 ED            IN AX,DX           ;IN FROM AI STATUS REG
CONV: 00A9 25 0001    AND AX,0001H     ;MASK ALL BUT BIT 0
00AC 75 FA          JNZ CONV          ;REPEAT IF BIT 0 NOT 0

; Enable Reading of AD# Channel
00AE BA 02E2        MOV DX,02E2H      ;REG 0, AD# INPUT, LO
00B1 B8 0000        MOV AX,0          ;ENABLE READING, LO B
;ZERO AH FOR FUTURE IN
00B4 EE            OUT DX,AL          ;OUTPUT LOW BYTE
00B5 BA 02E3        MOV DX,02E3H      ;REG 0,A/D 0 INPUT,HI
00B8 8A C3          MOV AL,BL         ;CODE FOR AD# 0 thru 3
00BA EE            OUT DX,AL          ;OUTPUT HIGH BYTE

; Read AD# Input (register 2--see p71)
00BB BA 22E2        MOV DX,22E2H      ;REG 2, AD# INPUT, LO
00BE ED            IN AX,DX           ;INPUT READING

;Subtract background from A/D inputs
00BF 57            PUSH DI            ;SAVE DATA ADDR.
00C0 BA 0200        MOV DX,0200H      ;BACKGROUND DATA
00C3 03 D3          ADD DX,BX         ; ADDRESS
00C5 03 D3          ADD DX,BX         ; + 2 TIMES
00C7 8B FA          MOV DI,DX         ; BL (AD#)
00C9 8B 15          MOV DX,[DI]       ;GET BACKGROUND
00CB 2B C2          SUB AX,DX         ;DIFFERENCE IN AX

;Store Difference in memory
; AD0-W, AD1-X, AD2-Y, & AD3-Z
00CD 5F            POP DI             ;DIFFERENCE ADDRESS
00CE 89 05          MOV [DI],AX       ;DIFFERENCE IN MEMORY
00D0 83 C7 08       ADD DI,8          ;INCREASE ADDR BY 8

;Obtain another AD# (channel # 1, 2 or 3)
00D3 FE C3          INC BL            ;INCREASE AD# BY 1
00D5 80 FB 04       CMP BL,4          ;IS BL > 3 i.e. (= 4)
00D8 75 AE          JNZ NEXTAD        ;NO? THEN REPEAT

;Take three ratios:
; AD1-X/AD0-W, AD2-Y/AD0-W, AD3-Z/AD0-W
00DA BB 0210        MOV BX,0210H     ;ADDR OF DIVISOR AD0-W
00DD 8B C3          MOV AX,BX         ;COPY INTO AX
00DF 05 0008        ADD AX,8          ;ADDRESS OF DIVIDEND
00E2 8B F8          MOV DI,AX         ; AD1-X IN DI
00E4 8B CB          MOV CX,BX         ;ADDR OF AD1-X/AD0-W
00E6 83 C1 20       ADD CX,20H        ; OFFSET FROM DIVISOR

```

```

00E9 8B F1          MOV SI,CX          ; BY 20H (IN SI)
00EB B9 0003        MOV CX,3          ; 3 RATIOS
00EE 9B DB 05        NXRAT: FILD DWORD PTR [DI] ;LD DIVIDEND-80287
00F1 9B DA 37        FIDIV DWORD PTR [BX];DIVIDE INTEGER
00F4 9B D9 1C        FSTP DWORD PTR [SI] ;STORE REAL & POP
00F7 83 C7 08        ADD DI,8          ;NEXT AD# DIFFERENCE
00FA 83 C6 08        ADD SI,8          ;NEXT AD# RATIO ADDR
00FD E2 EF          LOOP NXRAT         ;CALCULATE NEXT RATIO

```

```

;Sum the three ratios
00FF 83 C3 20        ADD BX,20H        ;ADDR OF AD1-X/AD0-W
0102 8B FB          MOV DI,BX          ; IN DI
0104 8B C3          MOV AX,BX          ;ADDR SUM AD1-X/AD0-W
0106 05 0020        ADD AX,20H        ; 20H HIGHER ADDR
0109 8B F0          MOV SI,AX         ; IN SI
010B B9 0003        MOV CX,3          ; 3 SUMS
010E 9B D9 04        NXSUM: FLD DWORD PTR [SI] ;LD REAL SUM
0111 9B D8 05        FADD DWORD PTR [DI] ;ADD REAL
0114 9B D9 1C        FSTP DWORD PTR [SI] ;STORE REAL & POP
0117 83 C7 08        ADD DI,8          ;ADDR OF NEXT RATIO
011A 83 C6 08        ADD SI,8          ;ADDR OF NEXT SUM
011D E2 EF          LOOP NXSUM         ;CALCULATE NEXT SUM

```

;Prepare to obtain another set of 4 AD# read.

```

011F BB 0210        MOV BX,0210H       ;OFFSET DATA ADDR.
0122 8B FB          MOV DI,BX          ; INTO PTR DI
0124 BB 0000        MOV BX,0000H       ;SELECT AD# = AD0
0127 59             POP CX             ;# READINGS REMAINING
0128 49             DEC CX             ; DECREASE BY 1
0129 E3 03          JCXZ MEAN          ;END IF CX = 0
012B E9 0055 R      JMP NEWSET         ;OTHERWISE LOOP

```

```

;Calculate mean (divide each sum by N)
012E B9 0003        MEAN: MOV CX,3          ; 3 GROUPS OF SUMS
0131 BB 0208        MOV BX,00208H      ;ADDRESS
0134 8B FB          MOV DI,BX          ; PTR FOR N
0136 BB 0250        MOV BX,0250H       ;OFFSET SUM ADDR.
0139 8B F3          MOV SI,BX          ; INTO PTR SI
013B 9B D9 04        NXMEAN: FLD DWORD PTR [SI] ;LOAD INTO 80287
013E 9B DA 35        FIDIV DWORD PTR [DI] ;DIVIDE BY N
0141 9B D9 1C        FSTP DWORD PTR [SI] ;STORE & POP MEAN
0144 83 C6 08        ADD SI,8          ;NEXT OFFSET SUM ADDR
0147 E2 F2          LOOP NXMEAN        ;REPEAT FOR NEXT MEAN

```

```

;Multiply by 10000d and change to integer
0149 BB 0268        MOV BX,0268H       ;ADDRESS OF MULTIPLIER
014C B8 2710        MOV AX,2710H       ;MOV+ 10000d MULTIPL.
014F 89 07          MOV [BX],AX        ; INTO ADDR. 0268H
0151 BA 0250        MOV DX,0250H       ;OFFSET MEAN ADDR
0154 8B FA          MOV DI,DX          ; POINTED TO BY DI
0156 BA 0270        MOV DX,0270H       ;ADDRESS OF ANSWER
0159 8B F2          MOV SI,DX          ; POINTED BY SI
015B B9 0003        MOV CX,3          ;REPEAT FOR 3 MEANS

```

```

015E 9B D9 05      CONINT: FLD DWORD PTR [DI] ;LOAD MEAN IN 80287
0161 9B DA 0F      FIMUL DWORD PTR [BX];MULTIPLY X 10000D
0164 9B DB 1C      FISTP DWORD PTR [SI] ;STORE & POP ANS
0167 83 C7 08      ADD DI,8 ;POINT NEXT MEAN
016A 83 C6 08      ADD SI,8 ;POINT NEXT ANSWER
016D E2 EF      LOOP CONINT ;NEXT CONVERT2INTEGER

;Stop After 3 ANSWERS in memory--short integer
016F 58      POP AX
0170 5E      POP SI
0171 1F      POP DS
0172 5D      POP BP
0173 90      NOP
0174 90      NOP
0175 CB      RET ;RTN BASIC
0176 90      NOP
0177 90      NOP

MAIN ENDP ;END OF MAIN PART OF PROGRAM
0178 0190[ DB 400D DUP(?) ;RESERVE DATA AREA
      ??
      ]

0308 ;-----
      PROGNAM ENDS
      ;*****
      END START ;END ASSEMBLY

```

## Segments and Groups:

N a m e	Size	Align	Combine Class
PROGNAM . . . . .	0308	PARA	NONE
ST_SEG . . . . .	00A0	PARA	STACK

## Symbols:

N a m e	Type	Value	Attr
CONINT . . . . .	L NEAR	015E	PROGNAM
CONV . . . . .	L NEAR	00A8	PROGNAM
FILL . . . . .	L NEAR	0044	PROGNAM
MAIN . . . . .	F PROC	0000	PROGNAM Length = 0178
MEAN . . . . .	L NEAR	012E	PROGNAM
NEWSET . . . . .	L NEAR	0055	PROGNAM
NEXTAD . . . . .	L NEAR	0088	PROGNAM
NXMEAN . . . . .	L NEAR	013B	PROGNAM
NXRAT . . . . .	L NEAR	00EE	PROGNAM
NXSUM . . . . .	L NEAR	010E	PROGNAM
START . . . . .	L NEAR	0000	PROGNAM
TRANS . . . . .	L NEAR	0097	PROGNAM

288 Source Lines  
288 Total Lines  
35 Symbols

49350 Bytes symbol space free

0 Warning Errors  
0 Severe Errors

C:\BG>

# TABLE IIIB ASSEMBLY LANGUAGE PROGRAM ALLEN7R.EXE

SYMDEB ALLEN7R.EXE

Microsoft (R) Symbolic Debug Utility Version 4.00

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Processor is [80286]

-R

AX=0000 BX=0000 CX=03A8 DX=0000 SP=00A0 BP=0000 SI=0000 DI=0000

DS=2E17 ES=2E17 SS=9FC0 CS=9FCA IP=0000 NV UP EI FL NZ NA PO NC

9FCA:0000 55

PUSH BP

-U0,177

9FCA:0000 55

PUSH BP

9FCA:0001 1E

PUSH DS

9FCA:0002 56

PUSH SI

9FCA:0003 8CC8

MOV AX,CS

9FCA:0005 8ED8

MOV DS,AX

9FCA:0007 2BC0

SUB AX,AX

9FCA:0009 50

PUSH AX

9FCA:000A BAE2C2

MOV DX,C2E2

9FCA:000D B80800

MOV AX,0008

9FCA:0010 EE

OUT DX,AL

9FCA:0011 BAE3C3

MOV DX,C3E3

9FCA:0014 B80000

MOV AX,0000

9FCA:0017 EE

OUT DX,AL

9FCA:0018 BAE222

MOV DX,22E2

9FCA:001B B80000

MOV AX,0000

9FCA:001E EE

OUT DX,AL

9FCA:001F BAE322

MOV DX,22E3

9FCA:0022 EE

OUT DX,AL

9FCA:0023 BAE222

MOV DX,22E2

9FCA:0026 B004

MOV AL,04

9FCA:0028 EE

OUT DX,AL

9FCA:0029 BAE322

MOV DX,22E3

9FCA:002C B000

MOV AL,00

9FCA:002E EE

OUT DX,AL

9FCA:002F BAE222

MOV DX,22E2

9FCA:0032 B000

MOV AL,00

9FCA:0034 EE

OUT DX,AL

9FCA:0035 BAE322

MOV DX,22E3

9FCA:0038 EE

OUT DX,AL

9FCA:0039 BB1002

MOV BX,0210

9FCA:003C 8BFB

MOV DI,BX

9FCA:003E B98000

MOV CX,0080

9FCA:0041 B80000

MOV AX,0000

9FCA:0044 8905

MOV [DI],AX

9FCA:0046 47

INC DI

9FCA:0047 E2FB

LOOP 0044

9FCA:0049 BB0802

MOV BX,0208

9FCA:004C 8B0F

MOV CX,[BX]

9FCA:004E BB1002

MOV BX,0210

9FCA:0051 8BFB

MOV DI,BX

9FCA:0053 B004

MOV AL,04

9FCA:0055 51

PUSH CX

9FCA:0056 BAE2C2

MOV DX,C2E2

9FCA:0059 B80800

MOV AX,0008

9FCA:005C EE

OUT DX,AL

9FCA:005D BAE3C3

MOV DX,C3E3

9FCA:0060 B80000

MOV AX,0000

9FCA:0063 EE

OUT DX,AL

9FCA:0064	BAE222	MOV	DX,22E2
9FCA:0067	B008	MOV	AL,08
9FCA:0069	EE	OUT	DX,AL
9FCA:006A	BAE322	MOV	DX,22E3
9FCA:006D	B000	MOV	AL,00
9FCA:006F	EE	OUT	DX,AL
9FCA:0070	BAE222	MOV	DX,22E2
9FCA:0073	B000	MOV	AL,00
9FCA:0075	EE	OUT	DX,AL
9FCA:0076	BAE322	MOV	DX,22E3
9FCA:0079	EE	OUT	DX,AL
9FCA:007A	BAE2C2	MOV	DX,C2E2
9FCA:007D	B009	MOV	AL,09
9FCA:007F	EE	OUT	DX,AL
9FCA:0080	BAE3C2	MOV	DX,C2E3
9FCA:0083	B000	MOV	AL,00
9FCA:0085	EE	OUT	DX,AL
9FCA:0086	2BDB	SUB	BX,BX
9FCA:0088	BAE202	MOV	DX,02E2
9FCA:008B	B000	MOV	AL,00
9FCA:008D	EE	OUT	DX,AL
9FCA:008E	BAE302	MOV	DX,02E3
9FCA:0091	8AC3	MOV	AL,BL
9FCA:0093	EE	OUT	DX,AL
9FCA:0094	B92200	MOV	CX,0022
9FCA:0097	E2FE	LOOP	0097
9FCA:0099	BAE202	MOV	DX,02E2
9FCA:009C	B001	MOV	AL,01
9FCA:009E	EE	OUT	DX,AL
9FCA:009F	BAE302	MOV	DX,02E3
9FCA:00A2	8AC3	MOV	AL,BL
9FCA:00A4	EE	OUT	DX,AL
9FCA:00A5	BAE202	MOV	DX,02E2
9FCA:00A8	ED	IN	AX,DX
9FCA:00A9	250100	AND	AX,0001
9FCA:00AC	75FA	JNZ	00A8
9FCA:00AE	BAE202	MOV	DX,02E2
9FCA:00B1	B80000	MOV	AX,0000
9FCA:00B4	EE	OUT	DX,AL
9FCA:00B5	BAE302	MOV	DX,02E3
9FCA:00B8	8AC3	MOV	AL,BL
9FCA:00BA	EE	OUT	DX,AL
9FCA:00BB	BAE222	MOV	DX,22E2
9FCA:00BE	ED	IN	AX,DX
9FCA:00BF	57	PUSH	DI
9FCA:00C0	BA0002	MOV	DX,0200
9FCA:00C3	03D3	ADD	DX,BX
9FCA:00C5	03D3	ADD	DX,BX
9FCA:00C7	8BFA	MOV	DI,DX
9FCA:00C9	8B15	MOV	DX,[DI]
9FCA:00CB	2BC2	SUB	AX,DX
9FCA:00CD	5F	POP	DI
9FCA:00CE	8905	MOV	[DI],AX
9FCA:00D0	83C708	ADD	DI,+08
9FCA:00D3	FEC3	INC	BL
9FCA:00D5	80FB04	CMP	BL,04
9FCA:00D8	75AE	JNZ	0088

9FCA:00DA	BB1002	MOV	BX,0210
9FCA:00DD	8BC3	MOV	AX,BX
9FCA:00DF	050800	ADD	AX,0008
9FCA:00E2	8BF8	MOV	DI,AX
9FCA:00E4	8BCB	MOV	CX,BX
9FCA:00E6	83C120	ADD	CX,+20
9FCA:00E9	8BF1	MOV	SI,CX
9FCA:00EB	B90300	MOV	CX,0003
9FCA:00EE	9B	WAIT	
9FCA:00EF	DB05	FLD	DWord Ptr [DI]
9FCA:00F1	9B	WAIT	
9FCA:00F2	DA37	FIDIV	DWord Ptr [BX]
9FCA:00F4	9B	WAIT	
9FCA:00F5	D91C	FSTP	DWord Ptr [SI]
9FCA:00F7	83C708	ADD	DI,+08
9FCA:00FA	83C608	ADD	SI,+08
9FCA:00FD	E2EF	LOOP	00EE
9FCA:00FF	83C320	ADD	BX,+20
9FCA:0102	8BFB	MOV	DI,BX
9FCA:0104	8BC3	MOV	AX,BX
9FCA:0106	052000	ADD	AX,0020
9FCA:0109	8BF0	MOV	SI,AX
9FCA:010B	B90300	MOV	CX,0003
9FCA:010E	9B	WAIT	
9FCA:010F	D904	FLD	DWord Ptr [SI]
9FCA:0111	9B	WAIT	
9FCA:0112	D805	FADD	DWord Ptr [DI]
9FCA:0114	9B	WAIT	
9FCA:0115	D91C	FSTP	DWord Ptr [SI]
9FCA:0117	83C708	ADD	DI,+08
9FCA:011A	83C608	ADD	SI,+08
9FCA:011D	E2EF	LOOP	010E
9FCA:011F	BB1002	MOV	BX,0210
9FCA:0122	8BFB	MOV	DI,BX
9FCA:0124	BB0000	MOV	BX,0000
9FCA:0127	59	POP	CX
9FCA:0128	49	DEC	CX
9FCA:0129	E303	JCXZ	012E
9FCA:012B	E927FF	JMP	0055
9FCA:012E	B90300	MOV	CX,0003
9FCA:0131	BB0802	MOV	BX,0208
9FCA:0134	8BFB	MOV	DI,BX
9FCA:0136	BB5002	MOV	BX,0250
9FCA:0139	8BF3	MOV	SI,BX
9FCA:013B	9B	WAIT	
9FCA:013C	D904	FLD	DWord Ptr [SI]
9FCA:013E	9B	WAIT	
9FCA:013F	DA35	FIDIV	DWord Ptr [DI]
9FCA:0141	9B	WAIT	
9FCA:0142	D91C	FSTP	DWord Ptr [SI]
9FCA:0144	83C608	ADD	SI,+08
9FCA:0147	E2F2	LOOP	013B
9FCA:0149	BB6802	MOV	BX,0268
9FCA:014C	B81027	MOV	AX,2710
9FCA:014F	8907	MOV	[BX],AX



9FCA:0151 BA5002	MOV DX,0250
9FCA:0154 8BFA	MOV DI,DX
9FCA:0156 BA7002	MOV DX,0270
9FCA:0159 8BF2	MOV SI,DX
9FCA:015B B90300	MOV CX,0003
9FCA:015E 9B	WAIT
9FCA:015F D905	FLD DWord Ptr [DI]
9FCA:0161 9B	WAIT
9FCA:0162 DA0F	FIMUL DWord Ptr [BX]
9FCA:0164 9B	WAIT
9FCA:0165 DB1C	FISTP DWord Ptr [SI]
9FCA:0167 83C708	ADD DI,+08
9FCA:016A 83C608	ADD SI,+08
9FCA:016D E2EF	LOOP 015E
9FCA:016F 58	POP AX
9FCA:0170 5E	POP SI
9FCA:0171 1F	POP DS
9FCA:0172 5D	POP BP
9FCA:0173 90	NOP
9FCA:0174 90	NOP
9FCA:0175 CB	RETF
9FCA:0176 90	NOP
9FCA:0177 90	NOP

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# Report Documentation Page

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15. Supplementary Notes Langley Technical Monitor: Edward V. Browell Final Report in support of the LASE Project to redefine the water vapor lines with improved accuracy in the 725-730 nm region. ALLEN ASSOCIATES, Subcontractor Robert J. Allen: Allen Associates, 205 Tabb Lane, Newport News, VA 23602					
16. Abstract An assembly language program using the Intel 80386 CPU and 80387 math co-processor chips was written to increase the speed of data gathering and processing, and provide control of a scanning CW ring dye laser system. This laser system is used in high resolution (better than 0.001 cm-1) water vapor spectroscopy experiments. Laser beam power is sensed at the input and output of white cells and the output of a Fabry-Perot. The assembly language subroutine is called from Basic, acquires the data and performs various calculations at rates greater than 150 faster than could be performed by the higher level language. The width of output control pulses generated in assembly language are 3 to 4 microseconds as compared to 2 to 3.7 milliseconds for those generated in Basic (about 500 to 1000 times faster). Included are a block diagram and brief description of the spectroscopy experiment, a flow diagram of the basic and assembly language programs, listing of the programs, scope photographs of the computer generated 5-volt pulses used for control and timing analysis, and representative water spectrum curves obtained using these programs.					
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